

4.1 Odredite mjerodavne sile po teoriji plastičnosti za nosač prikazan na crtežu.

Poznato je:

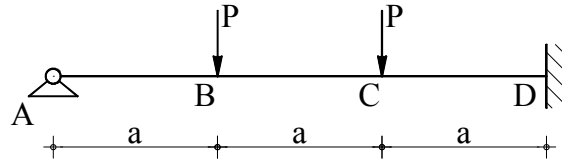
$$L = 6.0\text{m}$$

$$a = 3.0\text{m}$$

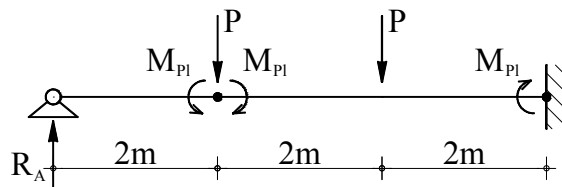
$$P = 60.0\text{kN}$$

$$\sigma_R = 21 \frac{\text{kN}}{\text{cm}^2}$$

$$v = 1.60$$



Plastična ravnoteža sustava:



Uvjet za moment plastičnosti u točki B

$$R_A \cdot a = M_{pl} \quad (1)$$

Uvjet za moment plastičnosti u točki D

$$R_A \cdot 3a - P \cdot 2a - P \cdot a = -M_{pl} \quad (2)$$

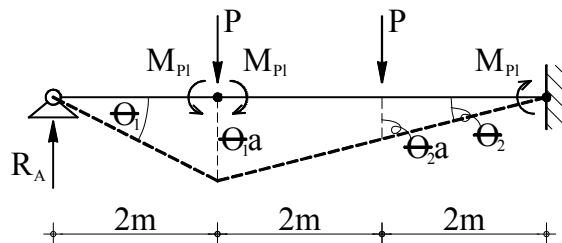
Kad uvrstimo jednačbu (1) u jednačbu (2) dobivamo:

$$\frac{M_{pl}}{a} \cdot 3a - P \cdot 2a - P \cdot a = -M_{pl}$$

$$3M_{pl} + M_{pl} = 3a \cdot P$$

$$M_{pl} = \frac{3}{4} P \cdot a = 90.0\text{kNm}$$

Kinematski princip /princip virtualnih radova/



$$P \cdot \Theta_1 \cdot a + P \cdot \Theta_2 \cdot a - M_{pl} \cdot \Theta_1 - 2 \cdot M_{pl} \cdot \Theta_2 = 0$$

$$\Theta_1 = 2\Theta_2 \Rightarrow P \cdot \Theta_1 \cdot a + P \cdot \frac{\Theta_1}{2} \cdot a - M_{pl} \cdot \Theta_1 - 2 \cdot M_{pl} \cdot \frac{\Theta_1}{2} = 0$$

$$\frac{P(2 \cdot \Theta_1 \cdot a + \Theta_1 \cdot a)}{2} = 2M_{pl} \cdot \Theta_1$$

$$M_{pl} = \frac{3}{4} P \cdot a = 90.0\text{kNm}$$